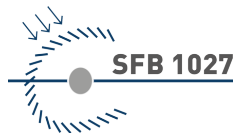




UNIVERSITÄT
DES
SAARLANDES

ZBP



THE NARROW ESCAPE PROBLEM IN A CIRCULAR DOMAIN WITH RADIAL PIECEWISE CONSTANT DIFFUSIVITY

MATTHIEU MANGEAT AND HEIKO RIEGER

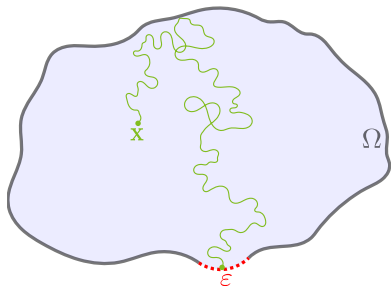
Center for Biophysics & Department for Theoretical Physics, Universität des Saarlandes,
D-66123 Saarbrücken, Deutschland

WEDNESDAY, OCTOBER 9th

Cell Physics 2019 - Saarland University

Narrow escape problem (NEP)

- ▶ Mean first passage time (MFPT) of Brownian motion (local diffusivity : $D(\mathbf{x})$) from a starting point (\mathbf{x}) to a small absorbing window (width : ε).
- ▶ Widely studied in last decades.
- ▶ Applications to chemical reaction kinetics, **intracellular transport...**



- ▶ Mathematical problem to solve :

$$\nabla \cdot D(\mathbf{x}) \nabla t(\mathbf{x}) = -1$$

$$t(\mathbf{x} \in \partial\Omega_\varepsilon) = 0$$

$$\mathbf{n} \cdot \nabla t(\mathbf{x} \in \partial\Omega \setminus \partial\Omega_\varepsilon) = 0$$

- ▶ Numerical evaluation of the MFPT :
 - ▶ PDE solver (e.g. FreeFem++)
 - ▶ Kinetic Monte Carlo (stochastic)

S. Redner, A Guide to First-Passage Processes, Cambridge University Press (2001)

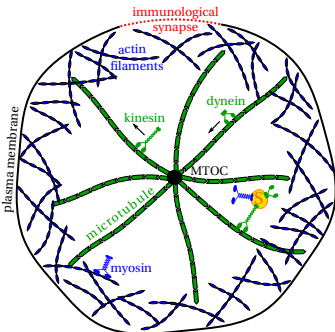
O. Bénichou and R. Voituriez, *Phys. Rev. Lett.* **100**, 168105 (2008)

F. Hecht, *J. Numer. Math.* **20**, 251 (2013)

K. Schwarz and H. Rieger, *Journal of Computational Physics* **237**, 396 (2013)

NEP in living cells

- ▶ NEP : intracellular cargo transport to immunological synapse located on cell membrane.
- ▶ Cargo : particle such as protein, vesicle, mitochondria, ...
- ▶ Spatial cytoskeleton organization with centrosome :



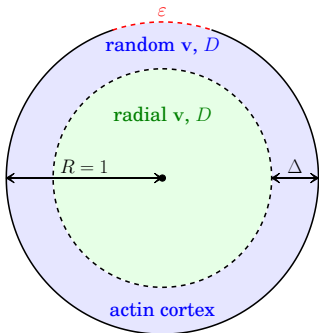
- ▶ Filaments :
 - ▶ polarized microtubules (radially distributed) → MTOC
 - ▶ actin filaments (randomly distributed), form actin cortex
- ▶ Molecular motor assisted motion (bind cargo & filaments)
 - ▶ dynein (periphery → center)
 - ▶ kinesin (center → periphery)
 - ▶ myosin (lateral transport)
- ▶ Stochastic alternation between two modes :
 - ▶ ballistic transport on filaments
 - ▶ cytoplasmic diffusion / stationary state ($D = 0$)

A. E. Hafner and H. Rieger, Biophysical Journal **118**, 1420 (2018)

P. C. Bressloff and J. M. Newby, Rev. Mod. Phys. **85**, 135 (2013)

NEP in living cells

- ▶ NEP : intracellular cargo transport to immunological synapse located on cell membrane.
- ▶ Cargo : particle such as protein, vesicle, mitochondria, ...
- ▶ Spatial cytoskeleton organization with centrosome :



- ▶ Filaments :
 - ▶ polarized microtubules (radially distributed) \rightarrow MTOC
 - ▶ actin filaments (randomly distributed), form actin cortex
- ▶ Molecular motor assisted motion (bind cargo & filaments)
 - ▶ dynein (periphery \rightarrow center)
 - ▶ kinesin (center \rightarrow periphery)
 - ▶ myosin (lateral transport)
- ▶ Stochastic alternation between two modes :
 - ▶ ballistic transport on filaments
 - ▶ cytoplasmic diffusion / stationary state ($D = 0$)

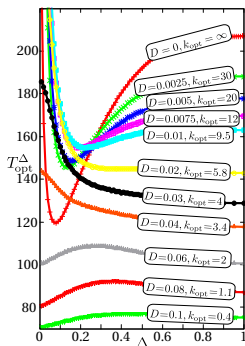
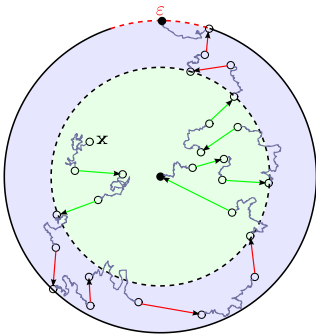
A. E. Hafner and H. Rieger, Biophysical Journal **118**, 1420 (2018)

P. C. Bressloff and J. M. Newby, Rev. Mod. Phys. **85**, 135 (2013)

- ▶ Optimization of MFPT \equiv **efficient intermittent search strategy.**

Efficient intermittent search strategies

- ▶ Small width of the actin cortex optimizes the MFPT for $D < 0.02$.
- ▶ Optimization more pronounced for small diffusivities.
- ▶ Random walk accelerated close to the boundary.

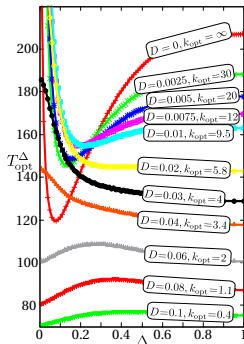
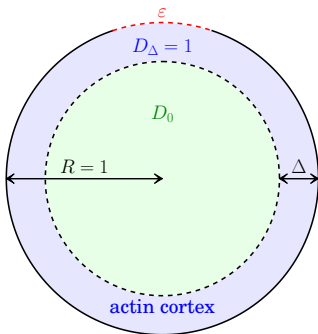


K. Schwarz, Y. Schröder, B. Qu, M. Hoth and H. Rieger, Phys. Rev. Lett. **117**, 068101 (2016)

A. E. Hafner and H. Rieger, Phys. Biol. **13**, 066003 (2016)

Efficient intermittent search strategies

- ▶ Small width of the actin cortex optimizes the MFPT for $D < 0.02$.
- ▶ Optimization more pronounced for small diffusivities.
- ▶ Random walk accelerated close to the boundary.



Model studied here :

- ▶ Ballistic motion neglected
- ▶ Two-shell geometry :

$$D_\Delta > D_0$$

- ▶ Three parameters :

$$\epsilon, \Delta, D_\Delta/D_0$$

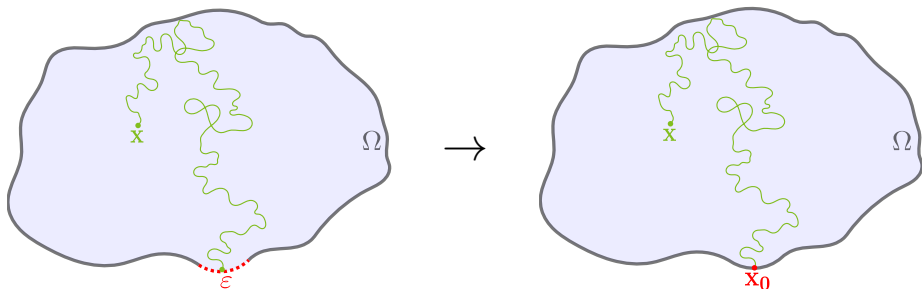
- ▶ circular domain with radial piecewise constant diffusivity

K. Schwarz, Y. Schröder, B. Qu, M. Hoth and H. Rieger, Phys. Rev. Lett. **117**, 068101 (2016)

A. E. Hafner and H. Rieger, Phys. Biol. **13**, 066003 (2016)

- ▶ What happens if the ballistic transport is neglected ?

Method : How to get narrow escape expressions ($\varepsilon \ll 1$) ?



$$D\nabla^2 t(\mathbf{x}) = -1$$

$$t(\mathbf{x} \in \partial\Omega_\varepsilon) = 0$$

$$\mathbf{n} \cdot \nabla t(\mathbf{x} \in \partial\Omega \setminus \partial\Omega_\varepsilon) = 0$$

$$t(\mathbf{x}) = \frac{|\Omega|}{\pi D} \left[-\ln \frac{\varepsilon}{4} + \pi R(\mathbf{x}_0|\mathbf{x}_0) - \pi G(\mathbf{x}|\mathbf{x}_0) \right]$$

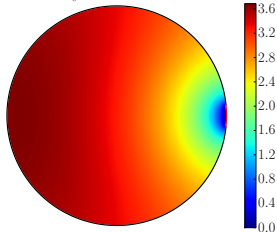
$$\nabla^2 G(\mathbf{x}|\mathbf{x}_0) = \frac{1}{|\Omega|}, \quad \int_{\Omega} d\mathbf{x} G(\mathbf{x}|\mathbf{x}_0) = 0$$

$$G(\mathbf{x} \rightarrow \mathbf{x}_0|\mathbf{x}_0) = -\frac{1}{\pi} \ln \frac{|\mathbf{x} - \mathbf{x}_0|}{R} + R(\mathbf{x}_0|\mathbf{x}_0)$$

$$\mathbf{n} \cdot \nabla G(\mathbf{x} \in \partial\Omega|\mathbf{x}_0) = 0$$

M. J. Ward and J. B. Keller, SIAM J. Appl. Math. **53**, 770 (1993)

S. Pillay, M. J. Ward, A. Peirce and T. Kolokolnikov, Multiscale Model. Simul. **8**, 803 (2010)

Known result : disk geometry ($D_\Delta = D_0$ or $\Delta = 1$) $D_0 = 1$ and $\varepsilon = 0.2$ 

- Narrow escape expression

$$t(\mathbf{x}) \underset{\varepsilon \ll 1}{\approx} \ln \frac{4|\mathbf{x} - \mathbf{x}_0|}{\varepsilon} + \frac{1 - |\mathbf{x}|^2}{4}$$

A. Singer, Z. Schuss and D. Holcman, J. Stat. Phys. **122**, 465 (2006)

- Global mean first passage time (GMFPT)

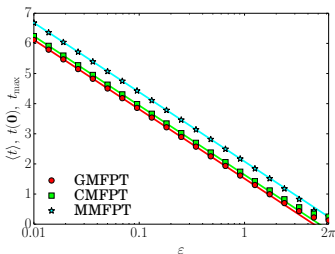
$$\langle t \rangle \underset{\varepsilon \ll 1}{\approx} -\ln \frac{\varepsilon}{4} + \frac{1}{8}$$

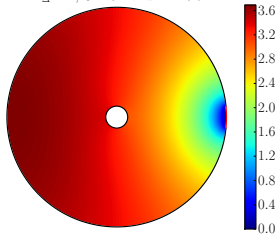
- Mean first passage time starting at the center (CMFPT)

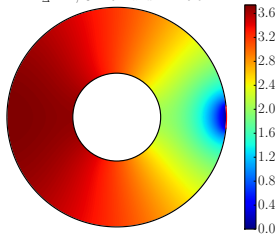
$$t(\mathbf{0}) \underset{\varepsilon \ll 1}{\approx} -\ln \frac{\varepsilon}{4} + \frac{1}{4}$$

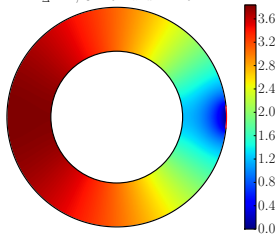
- Maximal mean first passage time (MMFPT)

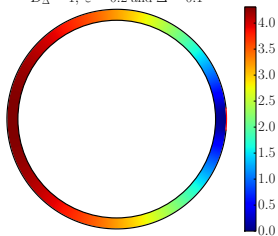
$$t_{\max} \underset{\varepsilon \ll 1}{\approx} -\ln \frac{\varepsilon}{4} + \ln 2$$

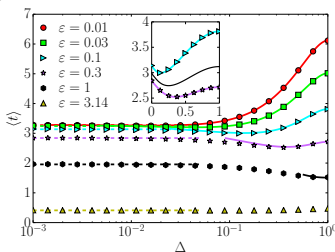
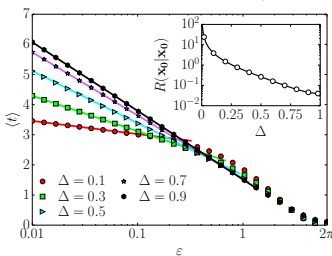
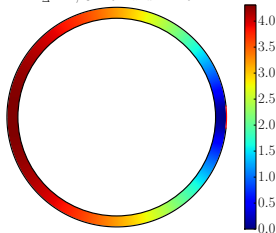


Annulus geometry ($D_0 = 0$) $D_\Delta = 1$, $\varepsilon = 0.2$ and $\Delta = 0.9$ 

Annulus geometry ($D_0 = 0$) $D_\Delta = 1$, $\varepsilon = 0.2$ and $\Delta = 0.6$ 

Annulus geometry ($D_0 = 0$) $D_\Delta = 1$, $\varepsilon = 0.2$ and $\Delta = 0.4$ 

Annulus geometry ($D_0 = 0$) $D_\Delta = 1$, $\varepsilon = 0.2$ and $\Delta = 0.1$ 

Annulus geometry $(D_0 = 0)$ $D_\Delta = 1$, $\varepsilon = 0.2$ and $\Delta = 0.1$ 

- Narrow escape expression ($\varepsilon \ll 1$) :

$$\langle t \rangle_{\varepsilon \ll 1} \simeq \Delta(2 - \Delta) \left[-\ln \frac{\varepsilon}{4} + \frac{3}{8} + 2 \sum_{n=1}^{\infty} \frac{(1 - \Delta)^{2n}}{n [1 - (1 - \Delta)^{2n}]} \right] - \frac{1}{4} - \frac{(1 - \Delta)^4 \ln(1 - \Delta)}{2\Delta(2 - \Delta)}.$$

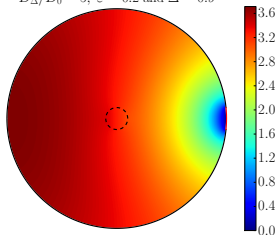
- Pseudo-one dimensional expression ($\Delta \ln \varepsilon \ll 1$) :

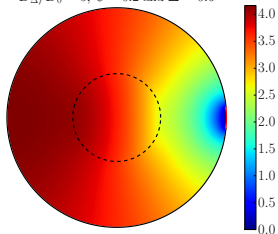
$$\langle t \rangle_{\Delta \ll 1} \simeq \frac{(2\pi - \varepsilon)^3}{24\pi}.$$

- General expression for $\Delta \ll 1$ and $\varepsilon \ll 1$:

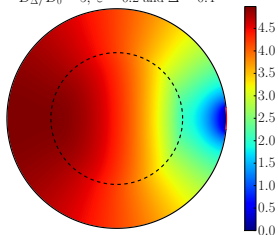
$$\langle t \rangle \simeq -2\Delta \ln \varepsilon + \frac{\pi^2}{3} + \mathcal{O}(\Delta, \varepsilon).$$

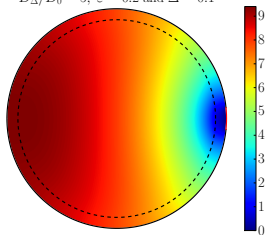
- MFPT optimized for $\varepsilon < 1$ due to the inner hardcore repulsion.

Two-shell geometry (fixed $D_{\Delta}/D_0 > 1$) $D_{\Delta}/D_0 = 5$, $\varepsilon = 0.2$ and $\Delta = 0.9$ 

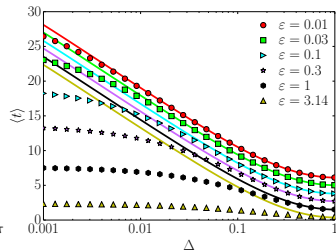
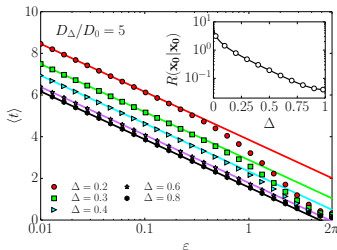
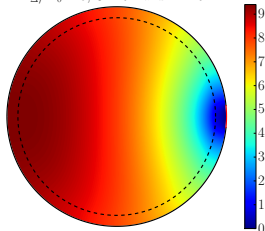
Two-shell geometry (fixed $D_{\Delta}/D_0 > 1$) $D_{\Delta}/D_0 = 5$, $\varepsilon = 0.2$ and $\Delta = 0.6$ 

M. Mangeat and H. Rieger, J. Phys. A : Math. Theor. **42**, 424002 (2019)

Two-shell geometry (fixed $D_{\Delta}/D_0 > 1$) $D_{\Delta}/D_0 = 5$, $\varepsilon = 0.2$ and $\Delta = 0.4$ 

Two-shell geometry (fixed $D_{\Delta}/D_0 > 1$) $D_{\Delta}/D_0 = 5$, $\varepsilon = 0.2$ and $\Delta = 0.1$ 

M. Mangeat and H. Rieger, J. Phys. A : Math. Theor. **42**, 424002 (2019)

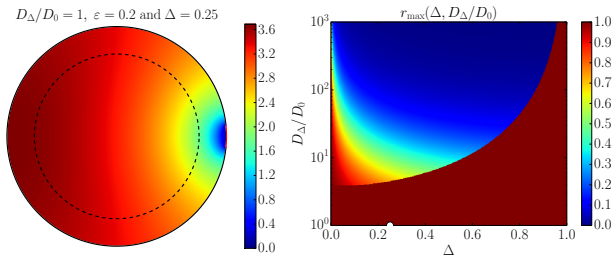
Two-shell geometry (fixed $D_\Delta/D_0 > 1$) $D_\Delta/D_0 = 5$, $\varepsilon = 0.2$ and $\Delta = 0.1$ 

- Narrow escape expression ($\varepsilon \ll 1$) :

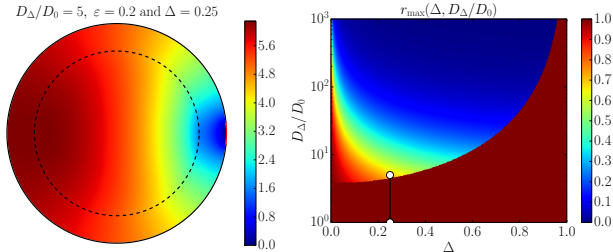
$$\langle t \rangle_{\varepsilon \ll 1} \simeq -\ln \frac{\varepsilon}{4} + \frac{1}{8} + \frac{D_\Delta - D_0}{8D_0} (1 - \Delta)^4 + 2 \sum_{n=1}^{\infty} \frac{(D_\Delta - D_0)(1 - \Delta)^{2n}}{n \{2D_0 + (D_\Delta - D_0)[1 - (1 - \Delta)^{2n}]\}}$$

- GMFPT decreasing function of ε at fixed Δ and D_Δ/D_0 .
- GMFPT decreasing function of Δ at fixed ε and D_Δ/D_0 .
- GMFPT go to a constant in the $\Delta \rightarrow 0$ limit.

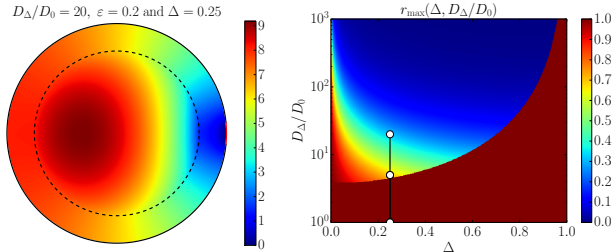
M. Mangeat and H. Rieger, J. Phys. A : Math. Theor. **42**, 424002 (2019)

Two-shell geometry (fixed $\Delta < 1$)

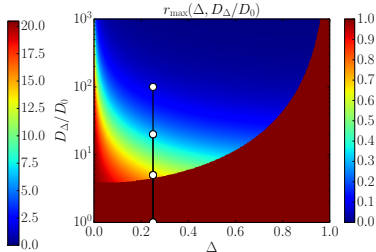
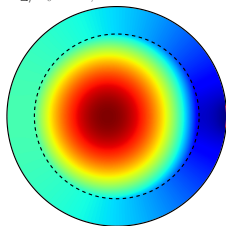
- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .

Two-shell geometry (fixed $\Delta < 1$)

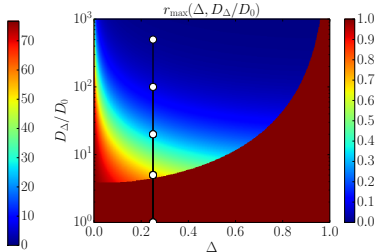
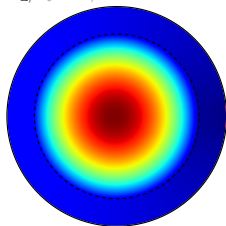
- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .

Two-shell geometry (fixed $\Delta < 1$)

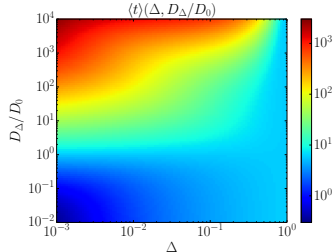
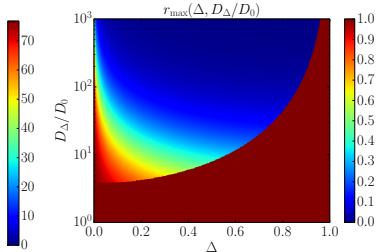
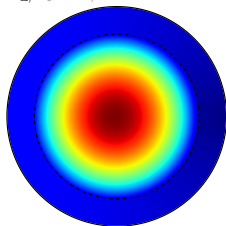
- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .

Two-shell geometry (fixed $\Delta < 1$) $D_\Delta/D_0 = 100$, $\varepsilon = 0.2$ and $\Delta = 0.25$ 

- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .

Two-shell geometry (fixed $\Delta < 1$) $D_\Delta/D_0 = 500$, $\varepsilon = 0.2$ and $\Delta = 0.25$ 

- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .

Two-shell geometry (fixed $\Delta < 1$) $D_\Delta/D_0 = 500$, $\varepsilon = 0.2$ and $\Delta = 0.25$ 

- ▶ Distance between starting position of MMFPT and center (r_{\max}) versus D_Δ/D_0 :
 - ▶ $D_\Delta/D_0 \in [1, D_c]$: like the disk geometry ($r_{\max} = 1$)
 - ▶ $D_\Delta/D_0 = D_c$: MMFPT starting position located in the inner shell ($r_{\max} < 1 - \Delta$)
 - ▶ $D_\Delta/D_0 \gg D_c$: MMFPT starting position goes continuously to the center ($r_{\max} \rightarrow 0$)
- ▶ r_{\max} is a decreasing and discontinuous function of D_Δ/D_0 .
- ▶ GMFPT increasing function of D_Δ/D_0 at fixed ε and Δ .
- ▶ GMFPT is a monotonous function of all parameters : **no optimization**.

- ▶ Analytical expression of MFPT obtained for circular domains in the narrow escape limit.
- ▶ For annulus geometry, the MFPT is optimized with the outer shell width Δ , due to hardcore repulsion.
- ▶ For two-shell geometry, the MFPT depends monotonously on the outer shell width Δ .
- ▶ For two-shell geometry, the distance between the starting position and the center which maximizes the MFPT depends discontinuously on D_{Δ}/D_0 .
- ▶ The MFPT can be optimized only when a mechanism enforce the particle to stay close to the surface : annulus geometry, intermittent search strategies, surface-mediated diffusion...

K. Schwarz, Y. Schröder, B. Qu, M. Hoth and H. Rieger, Phys. Rev. Lett. **117**, 068101 (2016)

A. E. Hafner and H. Rieger, Phys. Biol. **13**, 066003 (2016)

O. Bénichou, D. S. Grebenkov, P. E. Levitz, C. Loverdo, R. Voituriez, Phys. Rev. Lett. **105**, 150606 (2010)

- ▶ Make the boundary between the inner and outer shell semi-permeable.
- ▶ Introduce asymmetric reflection and transmission probabilities for the inner boundary.

Thank you for your attention !

List of publications :

- ▶ K. Schwarz, Y. Schröder, B. Qu, M. Hoth and H. Rieger, *Optimality of Spatially Inhomogeneous Search Strategies*, Phys. Rev. Lett. **117**, 068101 (2016)
- ▶ K. Schwarz, Y. Schröder and H. Rieger, *Numerical analysis of homogeneous and inhomogeneous intermittent search strategies*, Phys. Rev. E **94**, 042133 (2016)
- ▶ A. E. Hafner and H. Rieger, *Spatial organization of the cytoskeleton enhances cargo delivery to specific target areas on the plasma membrane of spherical cells*, Phys. Biol. **13**, 066003 (2016)
- ▶ A. E. Hafner and H. Rieger, *Spatial Cytoskeleton Organization Supports Targeted Intracellular Transport*, Biophysical Journal **118**, 1420 (2018)
- ▶ M. Mangeat and H. Rieger, *The narrow escape problem in a circular domain with radial piecewise constant diffusivity*, J. Phys. A : Math. Theor. **42**, 424002 (2019)